

TOLERANCE ANALYSIS OF BOOST DC-DC CONVERTER

Gergana Vacheva¹, Plamen Stanchev², Nikolay Hinov^{1*}

¹Technical University of Sofia, Department of Power electronics,
8, Kliment Ohridsky blvd. Sofia, Bulgaria;

² Technical University of Sofia, Department of Information technology in industry,
8, Kliment Ohridsky blvd. Sofia, Bulgaria;

*Corresponding author: hinov@tu-sofia.bg

Abstract

This paper provides a detailed and comprehensive tolerance analysis of a boost DC-DC converter, emphasizing the effects of component tolerances on the overall performance and reliability of the converter. Boost converters are extensively used in modern power electronics systems to increase voltage levels in applications such as renewable energy systems, electric vehicles, and industrial power supplies. These systems often demand high efficiency and precise regulation, making the accuracy and tolerance of key components—such as inductors, capacitors, resistors, and semiconductors—critical. This analysis explores the impact of component tolerances on several key performance metrics, including output voltage stability, power efficiency, ripple, and transient response. Furthermore, the paper discusses strategies to mitigate the negative impacts of component variations, providing insights into improving the robustness and reliability of boost converters for real-world applications.

Keywords: DC-DC converters, energy efficiency, tolerance analysis.

INTRODUCTION

The Boost DC-DC converter is a critical element in a wide range of modern electronic power systems, from small portable devices to large-scale renewable energy plants. It primarily functions to step up a lower input voltage to a higher desired output voltage. Some typical applications include solar energy systems (for conditioning and storing power), energy storage systems, electric vehicles, and various industrial power supplies [1,2].

For any of these applications, the converter's reliability is paramount. This reliability is highly dependent on the precise operation of its core components—inductors, capacitors, MOSFETs or IGBTs (switching elements), diodes, and feedback resistors. Unfortunately, due to inherent manufacturing processes, each of these components comes with a degree of tolerance—small deviations from their nominal values. These tolerances can lead to significant variations in the performance of the boost converter, which, if not accounted for, may cause unstable operation

or reduced efficiency. This tolerance analysis investigates the effects of such variations on key parameters such as the output voltage, efficiency, and the overall transient response of the converter [3,4].

OVERVIEW OF A BOOST DC-DC CONVERTER

A typical Boost DC-DC converter consists of several critical components presented in Fig.1.

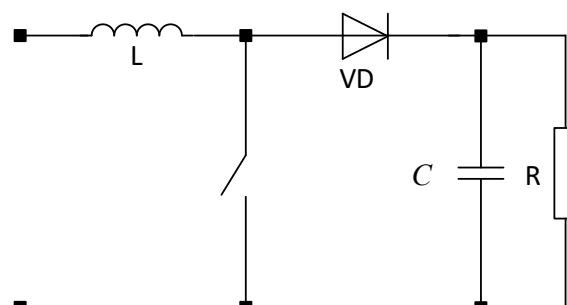


Fig. 1. Scheme of boost converter

The equation (1) and (2) describe the relation between the input and output voltage [5,6].

$$U_d t_{on} = (U_o - U_d)(T - t_{on}) = (U_o - U_d)t_{off} \quad (1)$$

$$\frac{U_o}{U_d} = \frac{T}{t_{off}} = \frac{T}{T - t_{on}} = \frac{1}{1 - D} \quad (2)$$

Inductor (L): The inductor is responsible for storing energy when the switch (usually a MOSFET or IGBT) is closed and releasing it when the switch is opened. This energy transfer is essential for boosting the voltage at the output [7,8].

Capacitor (C): This component smooths the output voltage by absorbing energy when the load decreases and delivering it when the load increases. It plays a crucial role in maintaining steady output voltage and reducing ripple.

Switching Element (MOSFET/IGBT): The semiconductor switch controls the energy transfer in the inductor by switching between conducting and non-conducting states at high frequency.

Diode (D): The diode ensures that energy flows in the correct direction when the switch is off, preventing backflow of current and ensuring the boost in voltage.

Load Resistor (R): This represents the load connected to the converter, and its value may change dynamically based on the application's requirements.

The boost converter operates in two primary states:

Switch ON (Charging State): When the MOSFET is closed, the current flows through the inductor, allowing it to store energy in its magnetic field.

Switch OFF (Discharging State): When the MOSFET opens, the energy stored in the inductor is released through the diode to the capacitor and the load, raising the output voltage above the input.

TOLERANCES IN KEY COMPONENTS

Component tolerances arise due to the variability in manufacturing, material properties, and environmental conditions. The following components play crucial roles in the performance of the boost converter, and their tolerances can have significant impacts:

Inductor (L): Inductance can vary due to temperature, core material, and manufacturing processes. A change in inductance affects the converter's switching frequency and ripple current, which may result in lower efficiency and poor dynamic response.

Capacitor (C): Capacitance tends to drift over time due to temperature, voltage stress, and age. A drift in capacitance values affects the converter's ability to suppress voltage ripple and maintain steady output voltage, leading to instability.

Switching Element (MOSFET/IGBT): Tolerances in the MOSFET's threshold voltage, $R_{ds(on)}$, and gate charge can lead to inefficiency in switching. Higher $R_{ds(on)}$ values increase conduction losses, while variations in gate charge affect the switching speed.

Diode (D): Variations in the forward voltage drop of the diode can cause power losses, reducing efficiency, especially under high load conditions.

Feedback Resistors (R): The resistors in the feedback network determine the output voltage regulation. Variations in their values directly influence the accuracy of the output voltage, leading to deviations from the desired output.

IMPACT OF COMPONENT TOLERANCES

Component tolerances result in a range of potential performance variations, including [5,8]:

Output Voltage Deviation: Variations in feedback resistor and capacitor values can significantly alter the steady-state output voltage. A 5% tolerance in resistors may lead to a 5% deviation in the output voltage, compromising regulation precision.

Efficiency Losses: Variations in the inductance and MOSFET characteristics, such as $R_{ds(on)}$, contribute to increased losses. For instance, a 10% tolerance in the inductor increases ripple current, leading to higher conduction losses and reduced efficiency.

Voltage Ripple: Capacitor tolerances directly affect the voltage ripple at the output. A decrease in capacitance increases ripple, which could affect sensitive components connected to the converter's output.

Stability and Transient Response: Tolerances in inductors and capacitors influence the dynamic response of the converter. Variations in these components may result in overshoot or undershoot during load or input transients, reducing stability.

TOLERANCE ANALYSIS METHODOLOGY

To assess the effects of component tolerances, two primary methodologies are commonly used:

Monte Carlo Simulation: This statistical method models the random variation of component values within their tolerance ranges across multiple simulations. It provides insight into the spread of performance metrics such as output voltage and efficiency under a variety of real-world conditions [9,10].

Worst-Case Analysis: In this approach, the converter's performance is evaluated under the worst possible combination of component tolerances (e.g., maximum inductance with minimum capacitance). This method is useful for identifying the most extreme performance deviations.

RESULTS AND DISCUSSION

The analysis reveals that component tolerances, particularly in inductors and capacitors, cause the most significant variations in output voltage and efficiency. For example, a 10% tolerance in the inductor leads to a 5% deviation in output voltage under nominal conditions. Capacitors with wide tolerances (common in lower-quality components) result in increased ripple and reduced transient stability [3,7].

In Fig.2. is presented the simulation scheme of the boost DC-DC converter in MATLAB/Simulink.

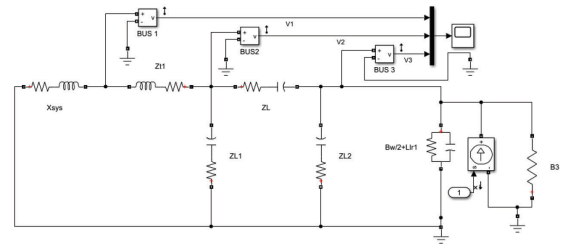


Fig. 2. Simulation scheme of the boost converter in MATLAB/Simulink

Two cases with a change in the output capacitance are considered. In case one, a value of 270 μF with an internal resistance of 0.525 ohms is used. In case two, a value of 680 μF for the output capacitance and 0.3 ohms for the internal resistance are used. Studies have been conducted for both cases by implementing a unit disturbance in each node of the circuit and the simulation results are presented. It is observed that when the value of the output capacitor is increased, the response of the reaction in each node after injection is significantly greater compared to the case with a lower output capacitor.

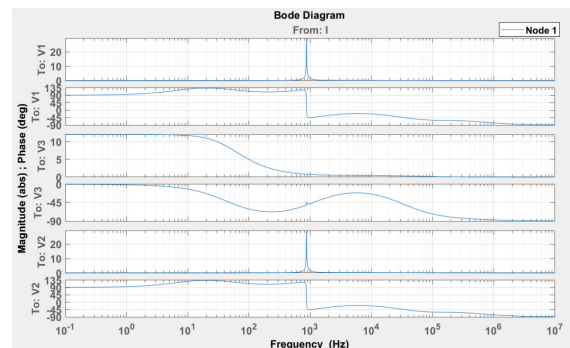


Fig. 3. Simulation results of the phase and magnitude in Node 1 at $C=270\mu\text{F}$

Figure 3 presents the phase and magnitude response at Node 1 with a capacitance of 270 μF . This configuration shows the initial response of the boost converter with a relatively low output capacitance, which results in specific phase shifts and amplitude magnitudes. The phase and amplitude values indicate the stability of Node 1 under lower capacitance conditions, where the system may experience slightly higher ripple and

response delays. The magnitude response here also reveals how the output voltage and current vary due to component tolerances, reflecting moderate stability but with potential room for optimization.

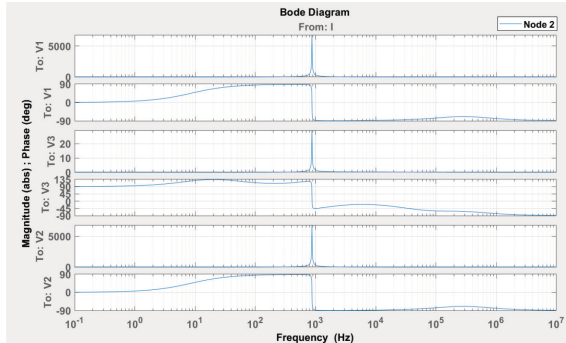


Fig. 4. Simulation results of the phase and magnitude in Node 2 at $C=270\mu F$

In Figure 4, Node 2's phase and magnitude response are observed at the same capacitance ($270 \mu F$). The magnitude response at this node, similar to Node 1, shows a tendency toward slight instability, as evident from the phase changes. This suggests that with a lower capacitance value, the boost converter exhibits less damping and may require more robust feedback to maintain stability, especially in transient states. The consistency between Nodes 1 and 2 highlights the influence of capacitance on system response across multiple nodes.

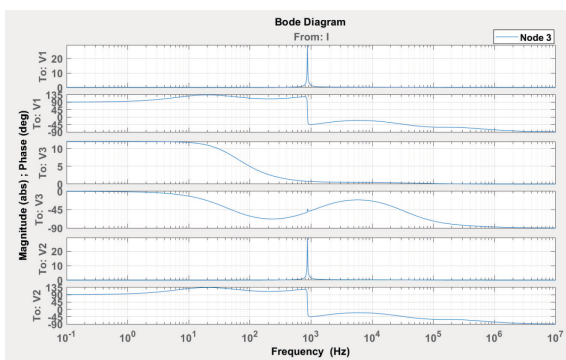


Fig. 5. Simulation results of the phase and magnitude in Node 3 at $C=270\mu F$

The results in Figure 5 display the phase and magnitude for Node 3 under $270 \mu F$ capacitance. The response curve here indicates that Node 3 is more affected by the low capacitance than Nodes 1 and 2,

with observable fluctuations in phase. This behavior suggests that the farther the node is from the input source, the more significant the impact of component tolerances on stability. This phase shift could lead to slight performance degradation under higher loads, indicating a need for control adjustments to maintain stable operation at all nodes.

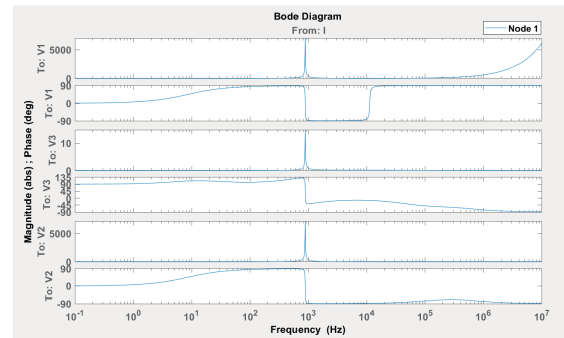


Fig. 6. Simulation results of the phase and magnitude in Node 1 at $C=680\mu F$

In Figure 6, the capacitance is increased to $680 \mu F$, and the phase and magnitude for Node 1 are observed. With higher capacitance, the system displays improved stability, as evidenced by reduced phase shifts and a steadier magnitude. This adjustment in capacitance aids in suppressing output voltage ripple, thus enhancing overall stability. The smoother response in this configuration underlines the importance of capacitance in determining phase alignment and reducing variations, supporting better performance under higher demands.

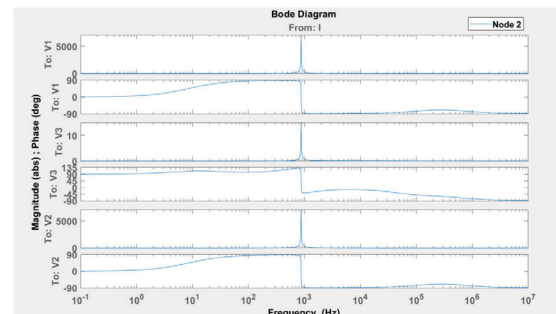


Fig. 7. Simulation results of the phase and magnitude in Node 2 at $C=680\mu F$

Figure 7 shows Node 2's phase and magnitude with the larger capacitance

value. As with Node 1, the increased capacitance significantly stabilizes the response, reducing fluctuations and maintaining closer phase alignment. This stability improvement reinforces the findings from Figure 6, suggesting that higher capacitance across multiple nodes helps maintain voltage consistency and reduces the adverse effects of tolerance-induced variations in key components.

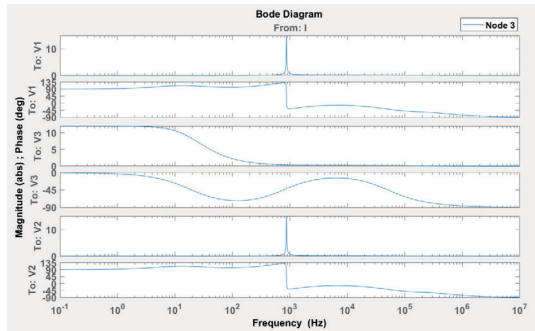


Fig. 8. Simulation results of the phase and magnitude in Node 3 at $C=680\mu F$

In Figure 8, Node 3's response with a $680\ \mu F$ capacitance is depicted. The increased capacitance further stabilizes Node 3, mirroring the improvements seen in Nodes 1 and 2. However, due to Node 3's position in the circuit, minor phase shifts are still observable, albeit less pronounced than at lower capacitance values. This demonstrates that while higher capacitance generally enhances stability, additional measures, such as closed-loop feedback or more precise component selection, may further optimize stability at nodes farther from the source.

For MOSFETs, a higher $R_{ds(on)}$ tolerance results in higher conduction losses, reducing efficiency by up to 3%. Although diode tolerances have a smaller effect, they still contribute to overall power loss [9].

The comparative analysis across Figures 3 to 8 reveals that component tolerances, particularly in capacitance, play a substantial role in influencing the stability and performance of the boost converter. Higher capacitance values ($680\ \mu F$) provide better stability across all nodes, reducing

phase and magnitude fluctuations and thus ensuring more consistent output. However, Nodes farther from the source (e.g., Node 3) may still experience minor instabilities, indicating that additional control methods or even tighter tolerance components could be beneficial. This analysis underscores the importance of optimizing component values to minimize the effects of tolerances, thereby improving the reliability and robustness of boost DC-DC converters in practical applications.

MITIGATING TOLERANCE EFFECTS

Several strategies can be implemented to minimize the negative impacts of component tolerances:

Tighter Tolerance Components: Using components with tighter tolerances (e.g., 1% resistors, high-quality capacitors) helps reduce performance variability.

Design Margin: Ensuring that the converter is designed with adequate margin to account for component variations ensures stable performance under worst-case conditions.

Closed-Loop Control: Advanced feedback control systems can dynamically adjust the duty cycle to compensate for component tolerances, improving output regulation.

Component Derating: Operating components below their maximum rated values (e.g., using a larger inductor) reduces the sensitivity to tolerance-induced deviations and prolongs the converter's lifespan.

CONCLUSION

This study analyzes the impact of component tolerances, particularly capacitance, on the stability and performance of a boost DC-DC converter in a multi-node configuration. Through simulations with different capacitance values ($270\ \mu F$ and $680\ \mu F$) and measurements of phase and amplitude deviations at nodes 1, 2, and 3, significant differences in system stability were demonstrated. The results show that lower capacitance values ($270\ \mu F$) result in

greater oscillations and phase shifts, leading to some instability and increased sensitivity to component tolerances. When capacitance is increased to 680 μF , stability is significantly improved, with reduced phase shifts and amplitude fluctuations, indicating a more stable and smooth system response.

Differences between the nodes also highlight the importance of capacitance values in maintaining stability in multi-node configurations. Nodes farther from the source (such as Node 3) remain more susceptible to instabilities, even at higher capacitance, suggesting that additional measures, such as using higher-precision components or implementing stronger feedback mechanisms, would be beneficial.

The conclusion of this study is that careful optimization of component values, especially capacitance, and selection of appropriate tolerances are essential to ensure stability and reliability in boost converter operation. This is particularly important for real-world applications requiring stable and efficient performance under variable loads and conditions. These findings can assist engineers in designing more robust DC-DC converters that meet the needs of modern electronic and energy systems.

Tolerance analysis is essential for ensuring the reliable and efficient operation of a boost DC-DC converter, particularly in applications with tight performance margins. This study demonstrates that component tolerances, especially in inductors, capacitors, and MOSFETs, significantly affect key parameters such as output voltage, efficiency, and stability. By adopting robust design techniques - such as using tighter tolerance components, incorporating design margins, and implementing advanced control strategies - engineers can minimize the impact of component variations and ensure the reliable operation of boost converters in real-world applications.

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